بسم الله الرحمن الرحيم



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Smart Cradle

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In the name of "Allah", the most beneficent and merciful who gives us strength, and knowledge and helped us to get through this study

We want to express our sincere gratitude to several individuals for supporting us throughout our academic careers. First, we wish to express our sincere gratitude to our supervisors, Dr. Radwan Tahboub and Eng. Wael Takrouri.

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ABSTRACT

Parents face taking care of their infant especially if both parents are working. Giving 24 hours in such cases is next to impossible. Thus, we need to develop something unique which can help parents to detect every activity of the Baby from home and at any distance in the world.

Thus, designing a smart cradle, where the system alerts parents of situations that would alleviate sudden infant death syndrome (SIDS), a condition that occurs in children under the age of 12 months, such as sleeping on the stomach, sleeping on a soft surface, high temperature, and cover the child with heavy blankets. The system will also measure the child's temperature to monitor it, as the system will alert parents of the child's high or low temperature, in addition, it measures the temperature of the surrounding atmosphere, which would provide a suitable atmosphere for him by operating an air conditioning system. When the baby is crying, the system is equipped with a camera and a microphone, the mother can talk to him, thus she may calm him down, or operate the rocking mechanism of the cradle, the system will operate under a certain frequency range. To reduce his crying, play a musical game to entertain the baby.

Keywords:

Smart Cradle, Sudden Infant Death Syndrome (SIDS).

الملخص

يواجه الوالدان صعوبة رعاية طفلهما الرضيع خاصة إذا كان كلا الوالدين يعملان. إن إعطاء 24 ساعة في مثل هذه الحالات هو أقرب

إلى المستحيل. وبالتالي ، تحتاج إلى تطوير شيء فريد يمكن أن يساعد الآباء على اكتشاف كل نشاط للطفل من المنزل وعلى أي مسافة في العالم.

وهكذا ، فإن تصميم مهد ذكي ، حيث ينبه النظام الآباء إلى المواقف التي من شأنها أن تخفف من متلازمة موت الرضع المفاجئ، وهي حالة تحدث عند الأطفال دون سن 12 شهرًا، مثل النوم على المعدة ، والنوم على سطح ناعم. ، ودرجة حرارة عالية ، وتغطية الطفل ببطانيات ثقيلة. كما سيقوم النظام بقياس درجة حرارة الطفل لرصدها ، حيث يقوم النظام بتنبيه الوالدين إلى ارتفاع أو انخفاض درجة حرارة الطفل ، بالإضافة إلى أنه يقيس درجة حرارة الجو المحيط ، مما يوفر له جوًا مناسبًا من خلال تشغيل الهواء. نظام التكييف. عندما يبكي الرضيع ، يكون النظام مزودًا بكاميرا وميكروفون ، يمكن للأم التحدث معه ، وبالتالي يمكنها تهدئته ، أو تشغيل آلية التأرجح في المهد ، وسيعمل النظام تحت نطاق تردد معين. للحد من بكائه.

الكلمات المفتاحية:

مهد ذكي, الرضيع ,متلازمة موت الرضيع المفاجئ.

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CHAPTER ONE INTRODUCTION

1.1 Preface

This chapter contains seven sections, the first section is about the motivations and importance of our project. It explains the reasons that make us believe in this project. The second section will be about the problem statement describing the problem we aim to solve. The third section will provide a short description of our project. The fourth section contains the objectives of our project. The fifth section represents the system requirement. The sixth section will provide the system limitations. The seventh section represents the project schedule.

1.2 Project Aims and Objectives

The main objectives of this system are:

The system alerts parents of situations that would alleviate sudden infant death syndrome (SIDS):

- Sleeping on the stomach.
- High temperature, and cover the baby with heavy blankets.

Accidental suffocation and suffocation in bed are among the most common causes of sudden death syndrome

Accidental Suffocation and Strangulation in Bed (ASSB) occurs when a baby is prevented from breathing due to soft bedding or a mattress and wall. It accounts for three-fourths of all unintentional injury fatalities in infants, with over 85% occurring from birth to six months, you can see this in the Figure 1.1 and how to reduce the risk of Accidental Suffocation and Strangulation in Bed [1].



Figure 1. 1ASSB by Baby's Age [2]

- Measures the temperature of the surrounding atmosphere.
- Operate the rocking mechanism of the cradle
- Measure the baby's temperature.

1.3 Problem Analysis and Statement

Taking care of the baby when they are months old is a great responsibility for the parents because they need special care and periodic monitoring, so what if the mother or father is working, or they spend time away from the baby? Hence there is a need for a smart system capable of monitoring the movement of the baby in his cradle, and giving reacting to the baby crying by informing his parents through an alarm, giving readings of the baby's temperature, and supporting remote control of the baby cradle by moving it when the baby cries. The project aims to solve all the abovementioned problems under the name of a smart cradle.

The project is a smart system that alarms parents when an abnormal situation for to baby occurs, such as sleeping on the stomach, in addition, measures the temperature of the baby and the surrounding atmosphere.

1.4 Problem Significance and Motivation

Under fast-paced life conditions, everyone, including parents, is busy professionally. They leave the house early in the morning and return before dinner. Even the mothers are working. Thus, they do not have sufficient time to care for their babies. Not all parents can afford a nanny to help them with their babies. Then, after working for long hours, the mothers still have to manage the house and take care of their babies simultaneously. Other parents may be occupied with house chores. Thus, because they cannot hear their baby crying, they cannot attend to them immediately. Sometimes, the baby only needs a little distraction to return to deep sleep.

In cases of a newborn child, the mother may be preoccupied for several reasons, including her health condition, which may not allow her to perform her functions as a mother to the fullest extent, in addition to that even if her health condition is good, housework may distract her from her child, and the wobbly sleep of the baby exposes her to Fatigue increases her need for rest, such as sleep, for example. This may result in exposing the child to danger, such as sudden clinical death, which is caused by

• Placing a baby on his side or stomach to sleep [3].

The aperture of the lungs' tube rests on top of the entrance of the stomach's tube while a newborn is lying on their back. Stomach fluids must overcome gravity to enter the windpipe and induce choking. as you see in Figure 1.2.



Figure 1. 2 Back Sleeping and SIDS [4]

- Premature or low birth weight babies [3].
- Overheating the baby during sleep [3].
- Sleeping on too soft a surface, with loose blankets and bumper pads [3].

The system allows parents to avoid the causes of this condition by monitoring the baby and alerting the parents in cases that may put him at risk.

1.5 Project Requirements

The system requirements are summarized as:

1.5.1 Functional Requirements

The main functional requirements of the system are:

Alert parents of situations that would alleviate sudden infant death syndrome (SIDS):

- Run a heater.
- Operate the rocking mechanism of the cradle.
- Remote access to the system.

1.5.2 Non-Functional Requirements

- Accuracy: Make sure the system is highly accurate in the position of the baby, such as sleeping on his stomach.
- Scalability: The system's capacity to be based on IOT
- Reliability: The system is intended function to do all it under stated conditions without failure for a given period.
- User-friendly system: Depending on the system's components and the technologies employed, the system and its application should be simple to use and comprehend for users.
- Maintainability: All components are easily serviceable and replaceable.
- Real-time: Real-time specifications include the length of time that must pass before an operation may be considered complete and is not subject to delay Informatics, in a smart cradle system, monitoring the baby's vital signs and the system's response to them must be subject to the concept of real-time, as the nature of the system from a medical perspective does not tolerate any delay. One of the most important requirements of this system is monitoring the baby and alerting in cases that may lead to sudden death syndrome. For example, if a child suffocates as a result of sleeping on his stomach, the child endures 30 seconds. When this period is exceeded, the child is exposed to health damage that ranges in severity from minor damage to serious damage such as brain damage or death.

Therefore, this system must apply the concept of real-time by responding immediately to any event that may result in health damage to the baby, it is assumed that the response of this system will be less than the period mentioned, which exposes the baby to danger, within a period ranging from 10 seconds. Here, the system must check the baby's condition and take readings such as temperature and pulse rate every 15 seconds.

1.7 Project Schedule

The team project started working on the smart cradle system from the planning stage, defining the exact project idea and functional requirements, then analyzing and designing the system through graphs, and finishing documentation in the last weeks. These steps have been traced over the semester, to achieve more effective result.

Time (each cell represents 2 weeks)

First Semester Second Semester

Planning

Project
requirement
Analyzing
and design

Documentation

Project
development

Project test
and
maintenance

Table 1. 1 Time Schedule Table

1.8 Report Outline

The rest of the report is organized as follows: Chapter 2 presents a theoretical background of the project. Chapter 3 introduces the system design, Chapter 4 explains implementation of the system, In Chapter 5 testing and result and Chapter 6 for conclusion and future work.

CHAPTER TWO THEORETICAL BACKGROUND

2.1 Preface

This chapter will describe the project's theoretical background and literature review.

2.2 Background

2.2.1 Sudden Infant Death Syndrome

In 1969, the National Institutes of Health consensus conference led to the first standardized definition of sudden infant death as the "sudden death of an infant or young child, which is unexpected by history, and in which a thorough postmortem examination fails to demonstrate an adequate cause of death" [5]. To identify a group of newborns with comparable features for whom vital data, research, and family counseling were required, the criteria required an autopsy for infants who died from a condition that was classified as SIDS. Many observers continued to consider SIDS as a single entity even though it was described as a syndrome and may thus be the outcome of multiple diseases because of its specific characteristics, which included:

- A peak incidence at 2 to 4 months of age,
- Intrathoracic petechiae are present.
- male predominance.

Further changes to the concept limited its use to infants younger than 12 months old, required an investigation of the death scene, or connected the death to sleep.

parents and caregivers can reduce the risk of SIDS and other sleep-related causes of infant death by guarding against several other sleep environment dangers. Some of these include:

2.2.1.1 Back Sleeping and SIDS

The single most effective action to lower a baby's risk of SIDS is to place the baby to sleep on their back for naps and at night. Stomach sleeping increases the risk of SIDS by 1.7 - 12.9 [4]. The mechanisms by which stomach sleeping might lead to SIDS are not entirely known, but studies suggest that stomach sleeping may increase SIDS risk through a variety of mechanisms, including:

- Increasing the probability that the baby re-breathes his or her own exhaled breath, leading to carbon dioxide buildup and low oxygen levels.
- Causing upper airway obstruction.
- Interfering with body heat dissipation, leading to overheating [4].

Researchers have established the link between stomach sleeping and SIDS by showing that babies who died from SIDS were more likely to be put to sleep on their stomachs compared to babies who lived. Public health campaigns were launched to promote the back sleep

position and reduce the use of the stomach sleep position. Public health campaigns have been successful in reducing the prevalence of stomach sleep position among infants.

This has resulted in dramatic decreases in SIDS rates in all countries, particularly in areas where stomach sleeping is rare. Compared to infants who sleep on their backs, and those who sleep on their stomachs.

2.2.1.2 Soft Sleeping Surfaces and Loose Bedding

According to studies, resting on soft surfaces like sofas and soft beds significantly increases the risk of SIDS. For instance, 2003 research found that putting a baby to sleep on soft bedding increased their risk of SIDS by five times compared to resting on solid bedding, such as a crib mattress that has received safety approval. The finding that infants who slept on their stomachs on soft bedding were 21 times more likely to die from SIDS than infants who slept on their backs on hard bedding was more startling.

Additionally, loose, soft bedding raises the chance of asphyxia. The Consumer Product Safety Commission has reported that the majority of sleep-related infant deaths in its database are related to suffocation involving pillows, quilts, and extra bedding [6]

2.2.1.3 Bed Sharing

Many mothers share a bed with their infant because it makes breastfeeding easier and enhances bonding. Studies do not support bed sharing as a protective approach for SIDS, even though some people think it may be since the parent is close to watching the infant.

Contrarily, mounting data suggest that sharing a bed increases the risk of SIDS and may also put a child in danger of asphyxia, entrapment, or harm. In some circumstances, sharing a bed increases the danger that is already there. When two people share a bed, for instance, the risk of SIDS is larger than either risk factor by itself. A mother who smokes, drinks lately, or feels exhausted. The baby is wrapped in a quilt or blanket. Several people share beds. According to studies, having other kids in bed more than multiplies the risk



Figure 2. 1 Bed Sharing [25]

of SIDS by five. In addition, bed-sharing exposes the newborn to extra hazards for unintentional harm and death, such as entrapment, falls, and strangling in an adult bed that is not intended for an infant. The biggest risk group includes infants under 4 months of age, as well as those who were delivered preterm or with low birth weight. This can be because it's challenging for them to adjust and avoid possible risks due to their weak muscles and motor abilities [7].

2.2.2 Introduction to Machine Learning:

Alan Turing's question "Can a machine think?" in 1955 suggested a test to gauge how intelligent a machine is. AI has grown quickly since then, and machine learning is a subset of AI that focuses on teaching algorithms to learn from data and get better over time.

Four machine learning algorithms are shown in Figure 2.2, briefly explaining the type of data each one needs.

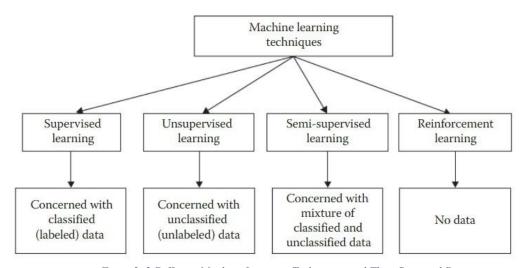


Figure 2. 2 Different Machine Learning Techniques and Their Required Data

The previous figure shows four different machine learning algorithms and the data required for each of them. The following is a definition of each type.

2.2.2.1 Supervised Learning [8]

Supervised learning is a type of education that infers a function from labeled training data, with two categories of algorithms: regression and classification.

2.2.2.2 Unsupervised Learning [8]

Unsupervised learning is difficult due to the lack of supervisors and training data, which can be inherently flawed or not enough resources to pay for manual labeling.

2.2.2.3 Semi-Supervised Learning [8]

Semi-supervised learning is a method of combining traditional and unclassified data to create an accurate model for categorization. It is similar to how we learn, with unlabeled information from the environment and labeled data from the supervisor.

2.2.2.4 Reinforcement Learning [8]

Reinforcement learning is an approach to creating intelligent programs that maximize reward or reduce risk using observations acquired through interactions with the environment.

Table 2.1 presents unlabeled data examples, with potential labels described in the third column. Machines can be employed in four scenarios, but their accuracy rates are questionable. Despite advancements in sentiment analysis, picture recognition, and speech detection, more work is needed before comparing their performance to humans. In tumor detection, even normal humans cannot label X-ray data.

Table 2. 1 Unlabeled Data Examples Along with Labeling Issues [8]

Unlabeled Data Example	Example Judgment for Labeling	Possible Labels	Possible Supervisor
Tweet	The sentiment of the tweet	Positive/negative	Human/machine
Photo	Contains a house and a car	Yes/No	Human/machine
Audio recording	The word football is uttered	Yes/No	Human/machine
Video	Are weapons used in the video?	Violent/nonviolent	Human/machine
X-ray	Tumor presence in X-ray	Present/absent	Experts/machine

2.3 Literature Review

In this section, we will talk about some projects similar to the idea of our project. To our knowledge, we did not find any similar projects in D space at Palestine Polytechnic University from 2014 to 2022.

Project outside the Palestine Polytechnic University researching scientific papers and previous articles related to the smart cradle and the smart cradle based on the Internet of Things. The following is a literature survey:

2.3.1 Literature Survey

Adults and older people can benefit from a variety of health care and health management systems. Numerous health statuses may be tracked, alerts can be sent automatically, and they have many other functions. However because these systems need to be utilized carefully, they cannot be employed practically for infants. Infants need entirely different healthcare than adults because they are dependent on their parents. Infants cannot comment on their health because they can only cry when they are uncomfortable. Therefore, to care for newborns, a properly constructed healthcare system is required. It would gradually lessen the load on parents, particularly mothers.

some smart health monitoring systems run on Android smartphones and are designed to collect raw data from wearable sensors before sending it to a microcontroller for processing.

After that, Bluetooth technology is used to wirelessly communicate the output to an Android smartphone. Some of the current health monitoring systems will use a GSM module to send an SMS message as a notification to the user's mobile phone [9].

Authors [10] developed a Raspberry Pi and Pi camera-based baby monitoring system. The system's design allows it to detect a baby's activity and crying patterns. With the aid of the Pi camera, they employed a condenser MIC to detect the crying state and a PIR motion sensor to detect the baby's movement. The camera is activated only when a sound is detected by the condenser MIC and a signal is sent to the Raspberry Pi. Parents can only view the data on a small number of devices within a fixed region because the output of this system is only visible on monitor display.

A monitoring system for an incubator was created. An infant is fitted with a pulse sensor to gauge their heart rate, and a humidity sensor gauges the relative humidity. The Neonatal Intensive Care Unit (NICU) staff can resort to the recorded data for diagnostic purposes by connecting the computer to the Arduino microcontroller. To avoid the occurrence of a harmful condition, an alarm system is created to send an alarm whenever the data readings reach a dangerous level. The system was tested on infants between the ages of 0 and 3 months, 3-6 months, and 6 to 12 months. However, only direct computer transfers were made of the captured data, Wi-Fi module can be added to this method to send data over the internet to track the newborns' conditions wherever they are.

The author of Paper [11] proposed a new algorithm that is crucial to improving baby care while parents are away has been proposed for our system. The data read by the sensors are gathered by the designed system's Node Micro-Controller Unit (NodeMCU) Controller Board and transmitted via Wi-Fi to the AdaFruit MQTT server. and their system used sensors to monitor the baby's vital parameters, including temperature, moisture, and crying.

In [12]the authors said that the external environment also serves as a cue when it's time to change a baby's diaper by assisting in the detection of increased body temperature, crying infants' voices, and their constant movements. Suppose any unusual behaviors are noticed in the baby's environment. The parents receive a warning notice. When the motion sensor picks up any sustained motions, the attached video camera, which is controlled by the microcontroller, starts recording a video. The parents are given access to the broadcasted footage through a display, allowing them to watch their child in real-time.

Additionally, this system monitors the condition of the baby, shows it, and notifies the appropriate adult by gathering data from sensors like temperature sensors, and ultrasonic sensors, via raspberry pi.

2.4 Summary

Our proposed system will be able to track the baby, especially his sleeping position, and give notifications to the parents. In addition, it has a camera that can record live pictures of the baby. It also has switches for turning the condition and the cradle swing on and off. This hybrid model incorporates the ideas suggested in the papers above.

CHAPTER THREE SYSTEM DESIGN

3.1 Preface

The following section has a description of the system, a detailed design, and necessary information about the design.

3.2 Design options

In this section, will talk about some design options for the system, where we will clarify the design in general and address two of the available options for dealing with video and images that are processed, before clarifying the available designs, the system will be clarified in general, by including it within three levels of input, output, and the control unit.

Turning to the inputs, we have a microphone to hear the baby's voice, a camera to monitor within the live stream mode, and a remote thermometer to monitor the temperature of the environment.

As for the outputs, we have a vibrating motor to shake the baby's bed, a speaker to hear the mother's voice, which works to calm the baby, a display screen to know the baby's pulse and the state of his sleeping position, an air conditioner that works in cold temperatures to provide a warm environment for the baby.

Finally, the controller, the brain of the system where the processing operations are for what is read to do one or more outputs to manage the system.

When a baby's crying signal is taken, the vibration motor will work to calm him down, and an alert will be made on the parent's application, which allows her to speak to the baby to hear his mother's voice, which works to calm him down until she reaches him, and at cold temperatures in the room, the hot air conditioner will work to raise the temperature surrounding the baby.

As for how to deal with the camera, we have two design options:

3.2.1 Storage-able System

This system discusses how to deal with the camera in the design of the smart children's bed using a storage unit, where the captured images will be stored in a storage unit attached to the system that can be replaced when it is full.

A picture of the child will be taken during specific periods to process it, know the child's sleeping position, and alert the parents when taking any of the positions that may lead to the child's suffocation and exposure to sudden infant death syndrome.

3.2.2 Non-Storage System

This system discusses how to handle the camera in designing a smart children's bed without using a storage unit. The captured images will be processed and a decision will be taken regarding them by ignoring them or giving an alert on the application if a situation applies to them that may lead to the child's suffocation and exposure to sudden infant death syndrome. Thus, it is an instantaneous processing of the captured image and a decision is taken to deal with it.

3.2.3 Summary

Thus, at the end of this section, we explained the design scheme in terms of inputs, outputs, and the controller, and we note the choice of the second design, which is a non-storable system, so that the project is intended to warn of child misfortunes that may result in death, and the lack of importance of having a recorded video, as the video needs a large storage space that may require Replacing the storage unit many times increases the cost, and every moment a parent wants to see the child, he can do so through a live broadcast, and thus the system will be implemented by choosing the second system, which is a system that cannot be stored.

3.3 System Component

This section is about the components and software we will use in our system, their alternatives, and the best options among them.

3.3.1 Mechanical Design

A baby cradle adapted to be rocked automatically, the action having the same effect as would be achieved by a mother rocking a cradle containing an infant, the cradle being pivotally supported at each end thereof to a support rack and stand. The motor also includes a regulating, reciprocating means for imparting the actuating movement of the crib in a smooth-rocking motion.

The mass of the cradle made of wood is about 15 kg with dimensions of 90cm, 60cm, and 70cm. As for the baby, its mass is estimated at 2.7 kg - 12 kg up to one year of age. The motor used can bear up to 60 kg/cm

3.3.2 Hardware Components

This section describes the hardware components used in the system.

1. Raspberry Pi 4

Raspberry Pi 4 was released with a 1.5 GHz 64-bit quad core ARM Cortex-A72 processor, on-board 802.11ac Wi-Fi, Bluetooth 5, full gigabit Ethernet (throughput not limited), two USB 2.0 ports, two USB 3.0 ports, 1, 2, 4, or 8 GB of RAM, and dual-monitor support via a pair of micro HDMI (HDMI Type D) ports for up to 4K resolution [13], this microcontroller is used to control all operations in the system, as shown in Figure 3.1.



Figure 3. 1Raspberry Pi 4

2. Raspberry Pi Camera

Raspberry pi camera has a flex cable inserts into the connector labelled CAMERA on the Raspberry Pi, which is located between the Ethernet and HDMI ports. The cable must be inserted with the silver contacts facing the HDMI port [14], It is used to monitor the baby remotely (streaming), as shown in Figure 3.2.

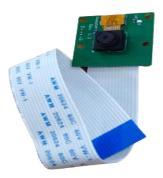


Figure 3. 2 Raspberry Pi Camera

3. Raspberry Pi Pico W

The raspberry pi pic W on-board 2.4GHz wireless interface has some features like, Wireless (802.11n), single-band (2.4 GHz), Soft access point supporting up to four clients, Bluetooth 5.2A [15]

This microcontroller will be placed on the baby's hand, to control the baby's heart rate and temperature, as shown in Figure 3.3.

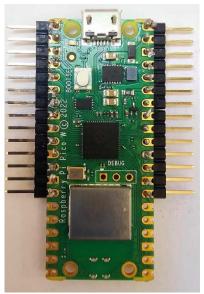


Figure 3. 3 Raspberry Pi Pico W

4. Wiper Motor

The motor activates linkage that moves the wiper arms back and forth on vehicles with a rear window wiper, it has 4 lines, in smart cradle system two lines for two speeds, one for motor driver and ground, It is used to rock the baby's cradle, as shown in Figure 3.4.



Figure 3. 4 Wiper Motor

5. DHT11 Sensor

DHT11 sensor has 3 pins, voltage, round and signal, It is used to measure the temperature around the baby, as shown in Figure 3.5.



Figure 3. 5 DHT11 Sensor

6. Heater and Fan

The conditioner will operate at two different levelsdul as heater if temperature falls below the ideal level. The Fan will turn on when the temperature is above the ideal level, as shown in Figure 3.6.



Figure 3. 6 Heater and Fan

7. MAX30205

MAX30205 works by i2c connection, by connect SDA, SCL with i2c channel in raspberry pi pico w, VCC and GND pins, it is used to measure the baby's temperature, as shown in Figure 3.7.



Figure 3. 7 MAX 30205

8. HR sensor

HR sensor has VCC, GND and a signal pin to review the heart rate data for the baby from his fingure, as shown in Figure 3.8.



Figure 3. 8 HR sensor [13]

9. Microphone and Speaker

Microphone connect to AUX port, and the speaker by Bluetooth, They used to communicate between the baby and the parents, as shown in Figure 3.9.



Figure 3. 9 Microphone and Speaker

10. Webcam

Webcam connect to Raspberry pi 4 USB port, It is used in the process of examining the position of the baby, as shown in Figure 3.10.



Figure 3. 10 Webcam [14]

3.3.3 Software Component

1. Teachable Machine [16]

Is a web-based tool that makes creating machine learning models fast, easy, and accessible to everyone, by training a computer to recognize baby images, sounds, and poses. Then, use the model to detect if SIDS occurs.

2. Thonny [17]

Thonny is a free and open-source IDE for Python, designed for beginners. It supports different ways of navigating through the code, step-by-step expression evaluation, detailed visualization of the call stack, and provides some Raspberry Pi-specific packages and libraries that make it easier to use.

3. MIT App Inventor [18]

MIT App Inventor (App Inventor or MIT AI2) is a high-level block-based visual programming language, originally built by Google. It allows newcomers to create computer applications for two operating systems: Android and iOS, It is free and

open-source and provides integration with different online services, such as Google Sheets and Firebase.

4. Google Firebase [19]

Google Firebase is a set of cloud-based development tools that helps mobile app developers build, deploy, and scale their apps. specifically used the real-time database.

Firebase Realtime Database is a cloud-hosted NoSQL database that allows organizations to store and sync data in real-time across all user devices. This makes it easy to create applications that are always up to date.

5. **Python [20]**

Python is used for developing Raspberry PI controller code, Python is an interpreted, object-oriented, high-level programming language with dynamic semantics Its high-level built-in data structures, combined with dynamic typing and dynamic binding, make it very attractive for Rapid Application Development, as well as for use as a scripting or glue language to connect existing components.

6. MicroPython [21]

MicroPython is a tiny open-source Python programming language interpreter that runs on small, embedded development boards. With MicroPython you can write clean and simple Python code to control hardware instead of having to use complex low-level languages like C or C++ (what Arduino uses for programming).

3.4 Design Components Options

This section is about the components and software we will use in our system their alternatives and the best option among them.

3.4.1 Microcontroller Alternative

This subsection illustrates the alternative for Raspberry Pi 4.

1. Raspberry Pi 4

Table 3.1 presents the difference between Raspberry Pi 4 and Banana Pi M5.

FEATURE	Banana Pi M5	Raspberry Pi 4B
Dimensions & Weight	92mm x 60mm, 48g	Single/dual
Memory	4GB LPDDR4	1GB, 2GB, 4GB, or 8GB LPDDR4-3200 SDRAM

Table 3. 1 Banana Pi M5 vs Raspberry Pi 4 [22].

Audio Output(s)	3.5 mm analog audio-video (or digital via HDMI)	3.5 mm analog audio-video jack (or digital via HDMI)
Network	Gigabit Ethernet; Wi-Fi and Bluetooth available via expansion boards	Gigabit Ethernet; 2.4 GHz and 5.0 GHz IEEE 802.11ac wireless; Bluetooth 5.0, BLE
GPIO	40-pin GPIO header (2x20 pins), 2.54mm pitch	40-pin GPIO header (2x20 pins), 2.54mm pitch
Dimension	85mm*56mm	28mm*55mm
price	\$35- \$55	\$64

3.4.2 Sensors

This subsection illustrates the alternative for ESP32.

1. DHT11

This subsection illustrates the alternative for DHT11:

• DHT11 vs DHT22

The DHT11 and DHT22 (AM2302) are Digital temperature sensors that monitor both temperature and humidity.

They have varied specifications but have very similar appearances and functions. As is shown in Table 3.2

Table 3. 2 DHT11 vs DHT22 [23].

Specifications	DHT11	DHT22
Measurement	Humidity and temperature	Humidity and temperature

Temperature Range	0 – 50° C / ± 2° C	-40 – 125° C / ± 0.5° C
Humidity Range	20 – 80 / ± 5 %	$0-100$ / ± 2.5 %
Sampling Rate	1 Hz one reading every second	0.5 Hz one reading every two seconds
Accuracy	+/- 2°C (at 0 to 50°C)	+/- 0.5°C (at -40 to 80°C)
Body size	15.5 mm × 12 mm × 5.5 mm	15.1 mm × 25 mm × 7.7 mm
Operating Voltage	3 – 5 V	3 – 5 V
Minimum current	2.5 mA	2.5 mA
Price	\$6.99	\$10.99

will utilize DHT11 in our project because it will provide the precision we need. We didn't employ a temperature sensor and a humidity sensor separately to cut down on the number of hardware components inside the system.

3.3.1.2 Wiper Motor for Car

- **stepper motor**: an electric motor whose main feature is that its shaft rotates by performing steps, that is, by moving by a fixed amount of degrees.
- **DC motor**: any of a class of rotary electrical motors that converts direct current (DC) electrical energy into mechanical energy, the wiper motor is an example of a DC motor.

Table 3.3 presents the difference between the Stepper Motor and DC Motor.

Table 3. 3 Stepper Motor vs DC Motor [24].

Characteristics	Stepper Motor 24v	DC Motor
Nature of loop	Open Loop	Closed Loop
Control characteristics	Easy to control with microprocessors	Not easy to control
Speed range	Low (Approximately 200-2000 RPMs)	Moderate (it depends on the motor type)
Reliability	High	Moderate
Efficiency	Low	Average
Torque/speed characteristics	Has maximum torque at low speeds	High torque at relatively low speeds
Cost	\$53	\$54
Size	1.93 x 1.65 x 2.72 inches	small

Will use a DC motor-specific wiper motor for the car, due to its low cost, small size, and can to connect with microcontrollers, in addition to the need to swing the baby's cradle.

3.5.1 Conceptual System Description

In this subsection, diagrams are represented for the understanding of the project concepts and design.

3.5.2 General Block Diagram

In this section, will talk about the General block diagram, the system will be clarified in general, by including it within three levels input, output, and control unit. As shown in the Figure 3.11 below.

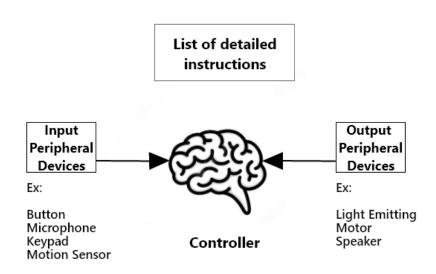


Figure 3. 11 General Block Diagram

Turning to the inputs, we have a microphone to hear the baby's voice, a camera to monitor the baby so that it is within the live stream mode, and a remote thermometer to monitor the temperature of the environment.

As for the outputs, we have a wiper motor to rock the baby's bed, a speaker to hear the mother's voice, which works to calm the baby, and the state of his sleeping position, an air conditioner that works in cold temperatures to provide a warm environment for the baby.

Finally, the controller, the brain of the system where the processing operations are for what is read to do one or more outputs to manage the system. The Raspberry Pi 4 microcontroller will use

When a baby crying signal is taken, the vibration motor will work to calm him down, and an alert will be made on the parent's application, which allows her to speak to the child to hear

his mother's voice, which works to calm him down until she reaches him, and at cold temperatures in the room, the hot air conditioner will work to raise the temperature surrounding the baby, and an alert will be given on When the child's temperature rises from the thermometer, the baby's pulse status will also be displayed on a window in the application read by the oximeter.

This scenario will reflect on the smart cradle system as Figure 3.12 shows.

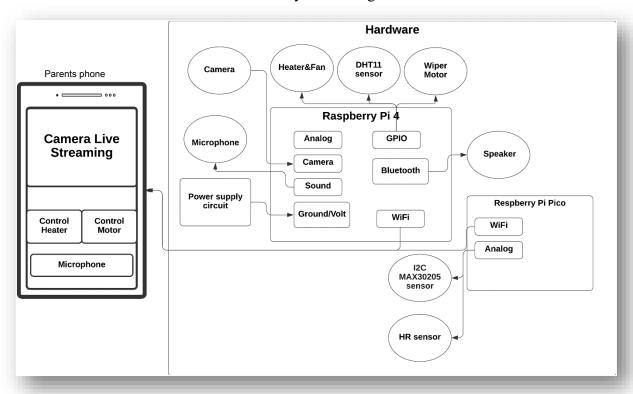


Figure 3. 12 General Block Diagram for The Smart Cradle System

3.5.3 Conceptual Diagram

Figure 3.13 represents the concept of the system.

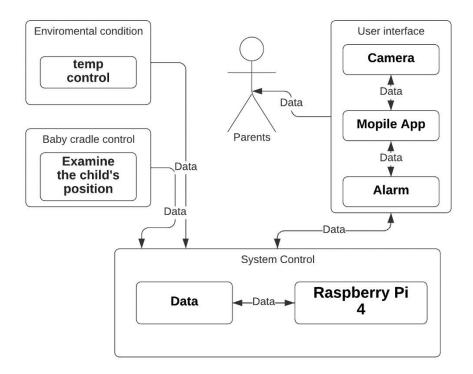


Figure 3. 13 Conceptual Diagram

3.6 Algorithms and Methodologies

In this section, we describe our system work by using a flow chart.

3.6.1 System Flow Chart

Figure 3.14 below represents the Raspberry Pi 4 flowchart.

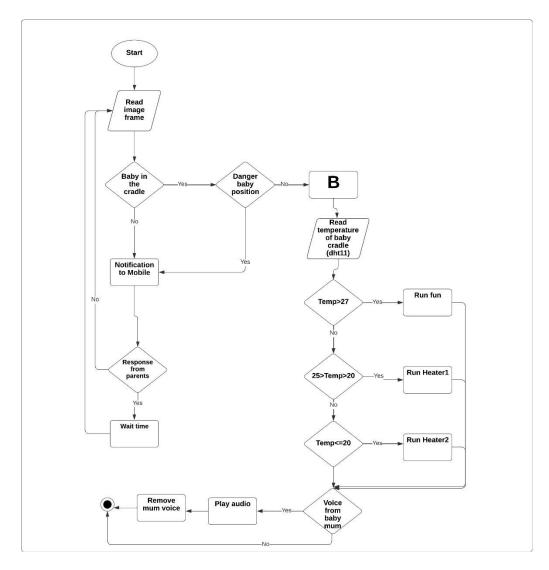


Figure 3. 14 Raspberry Pi 4 Flowchart

3.6.2 Sound and Swing Algorithm

Figure 3.15 below represents the sound algorithm of our system using a flowchart.

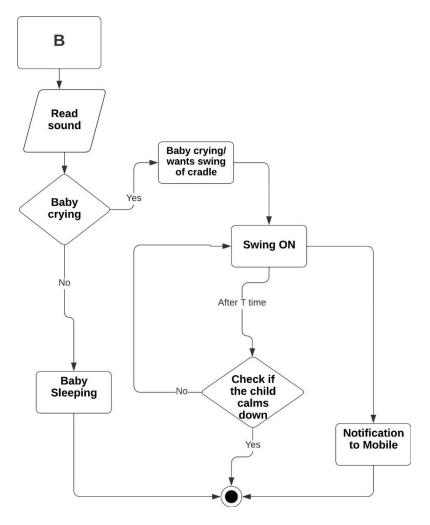


Figure 3. 15 Baby Crying Algorithm

Figure 3.16 below represents the Raspberry Pi Pico W system using a flowchart.

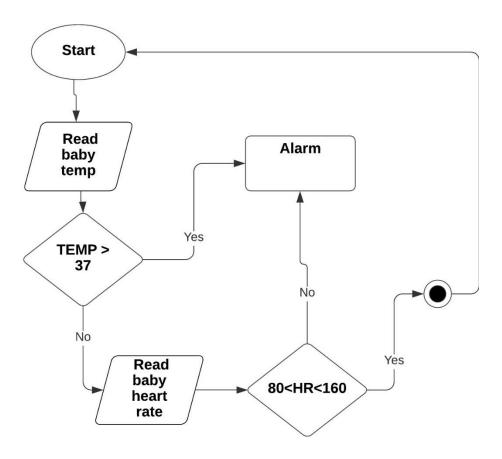


Figure 3. 16 Raspberry Pi Pico W Flowchart

3.7 Schematic Diagram

The Raspberry Pi Pico represents a simple smart watch to measure the baby's pulse and temperature. The max sensor is connected to the gp0 and gp1 pins, and the pulse sensor is connected to the signal GP27 pin.

Figure 3.17 represents a schematic diagram for Raspberry Pi Pico W.

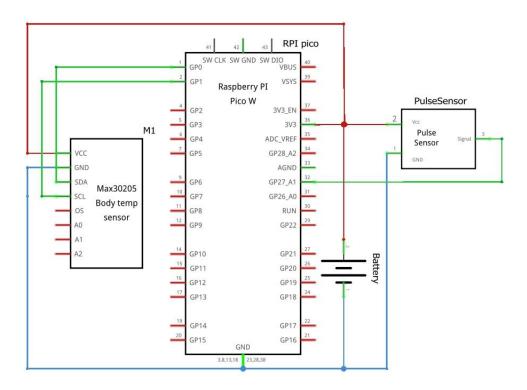


Figure 3. 17 Raspberry Pi Pico W Schematic Diagram

In the Raspberry Pi 4 microcontroller, the conditioner is connected to the relay, then to 3 GPIO4, GPIO5andGPIO26 as for the motor, it is also connected to a relay on pin gpio12. DHT11 sensor connect to gpio15, And both RPI camera and webcam with USB and the camera port on the Raspberry Pi, The microphone is connected to the aux port.

Figure 3.18 represents a schematic diagram for Raspberry Pi 4.

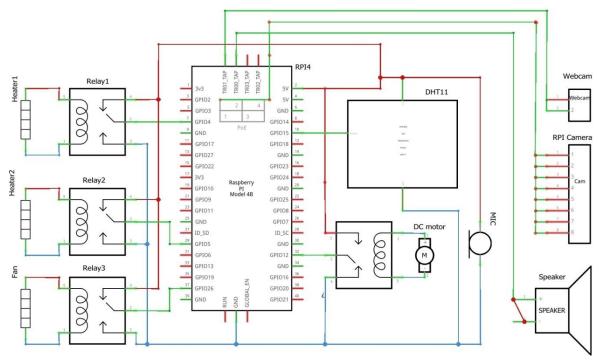


Figure 3. 19 Raspberry Pi 4 Schematic Diagram

3.8 Summary and Conclusion

In this chapter, we describe the design option, we talked about alternatives to the memoryless system that we will use in our project, and why we chose them. In the System component, we talk about mechanical design, hardware design, and software design. In mechanical design, we talk about the shape of the crib and the materials used to build it. In hardware design, we talk about components that we want to use and how they work together, and finally, we talk about software design

.

In the design components options, we talked about alternatives to the components that we will use in our project and why we chose them. Then we talk about conceptual system description by using a block diagram and conceptual model, and we use a flow chart in the algorithms and methodologies section.

CHAPTER FOUR

SYSTEM IMPLEMENTATION

4.1 Preface

This Chapter introduces a description of the implementation, implementation issues, implementation challenges, and description of the method used to validate the system.

4.2 Description of The Implementation

In this section, we explained software implementation tools and described how the system works.

4.2.1 Software Implementation Tools:

Python code is used to program the Raspberry Pi 4 microcontroller that will be on the cradle to perform a control operation like the cradle swing and conditioning.

To implement the application, firebase and MIT App Inventor are used.

4.2.1.1 Image Module

To create the image model, the teachable machine was used, where we started by collecting the data set and then divided it into 3 categories, which are that the baby is in a safe, dangerous position, and not exit. Figure 4.1 represent classification types on the teachable machine.

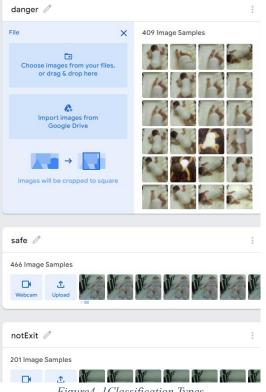


Figure 4. 1 Classification Types

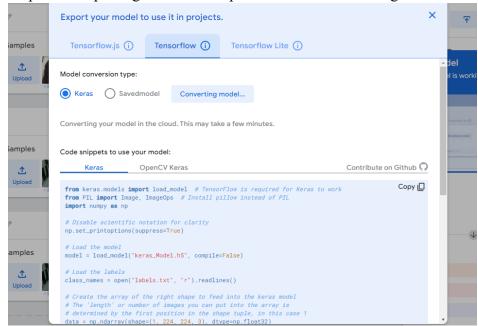


Figure 4.2 represent exporting model after upload data set and training.

Figure 4. 2 Exporting Model

4.2.2 Description of The Implementation:

The first step was to purchase the necessary parts and sensors, in addition to the microcontroller, Raspberry Pi 4, which tested all sensors and devices in an initial test, after studying the data sheets for each of them.

The MCU30205 and HR sensor are connected with the Raspberry Pi Pico w, and this separate system represents a smart bracelet that is placed on the baby's hand to take readings only, as shown in the figure below.

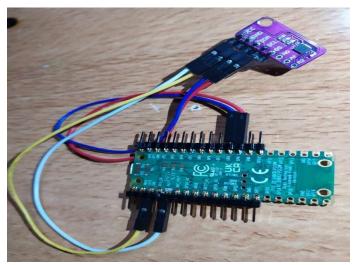


Figure 4. 3 MCU30205 with Raspberry Pi Pico W

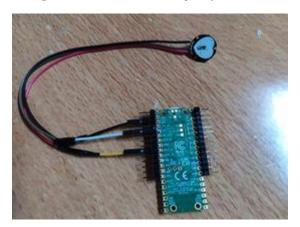


Figure 4. 4 HR sensor with Raspberry Pi Pico W

The Raspberry Pi 4, connects the speaker, a microphone, a webcam, a Raspberry Pi camera, the DC motor, and the DHT11 sensor, this system is placed on the cradle, so that it can take readings from the sensor and camera stream, in addition to taking actions such as swing the cradle and turning on the air conditioning, The following figure shows how to hang Raspberry pi 4 on the cradle.

As for the air conditioner, the user is allowed to control it manually, i.e. cold, hot, or automatically, based on the DHT11 sensor reading. Regarding the motor, also the user is allowed to control it manually, at more than one speed, or automatically, based on the sound model that determines whether it is the sound of a baby crying or a background sound.

Raspberry Pi camera is used for baby positions model so that it determines whether the baby's position exposes it to danger or is safe. A webcam for video streaming enables the user to

monitor the baby at any time, whether the baby exists in the cradle or not, noting that the system only works if the baby exists in the cradle.

The following images represent the interface between a component and Raspberry Pi 4 that was wired and tested.



Figure 4. 5 Microphone with Raspberry Pi 4



Figure 4. 6 Web Camera with Raspberry Pi 4

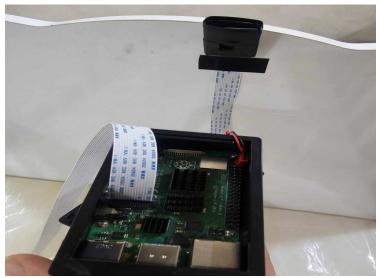


Figure 4. 7 Raspberry Camera with Raspberry Pi 4



Figure 4. 8 Wiper Motor with Raspberry Pi 4



Figure 4. 9 DHT11 Sensor with Raspberry Pi 4

After completing the connections of all sensors and devices, we connected the Raspberry Pi 4 to the Firebase. Specifically, we used Firebase Storage for the user audio and Firebase Realtime for all sensors and devices.

Finally, MIT App Inventor is used to create the application, provide a user interface for monitoring and control, and connect it with Firebase to send notifications such as the baby is in danger, or the baby is crying.

4.3 Application Implementation

The app was developed using MIT App Inventor, it is a good tool for mobile implementation applications, whether for Android or IOS.

When the user opens the application, the program directs the user to the login page, as each user has an account, so that he can enter the system of Smart Cradle, and this is to enhance security. There is also a Sign-Up page if the user has not previously logged into the system.

After that, the user is taken to the next page, which contains a Web Viewer to view streaming video directed to the cradle, in addition to buttons to control and play a record from the user to the baby.

The fourth and last page enables controlling the air conditioner and the speed of the DC motor.

These are images of our mobile application pages.

1. In first the user should create an account by signing up, as shown in the Figure 4.10 below.

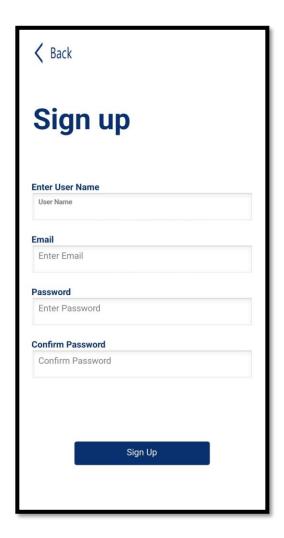


Figure 4. 10 Sign-Up Page

Or if the Parent has an account, he login to it, as shown in the Figure 4.11 below.

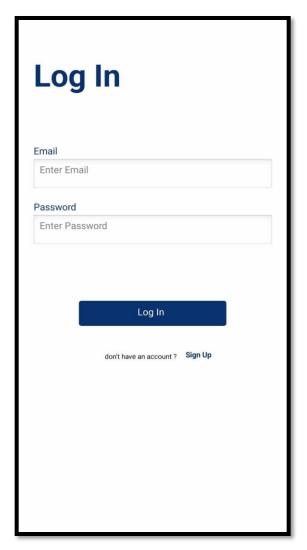


Figure 4. 11 Log-In Page

2. The following figure is the controlling page where a parent can find sensor readings, DC motor, and air conditioner controlling, as shown in Figure 4.12 below.

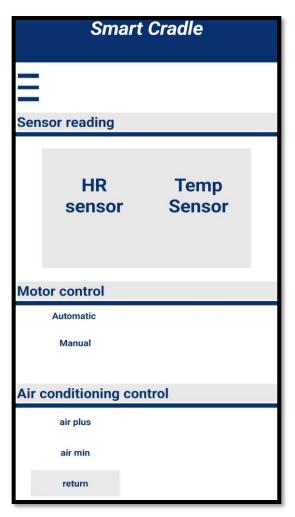


Figure 4. 12 Controlling Page

3. The following figure is a home page containing video streaming and a button to record a voice. as shown in Figure 4.13 below.

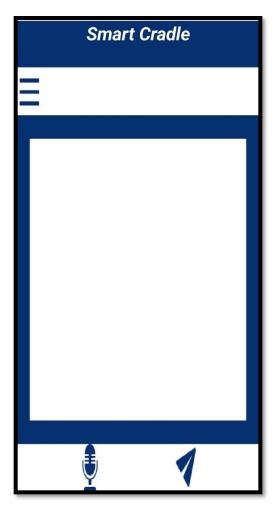


Figure 4. 13 Home (video and record) Page

4. The following figure is the menu page which contains log out, home, and settings, as shown in Figure 4.14.

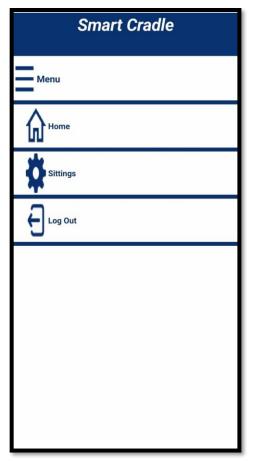


Figure 4. 14 Menu Page

4.4 Implementation Challenges

- 1. We faced problems in purchasing some sensors due to the closure of roads because of the aggression in Gaza, so we found an alternative to some sensors.
- 2. The versions of some libraries were not compatible with the version of the sensor or microcontroller. We solved this problem by creating a virtual environment and downloading all the libraries into it.
- 3. The Raspberry Pi 4 only has one AUX audio input, so we connected the microphone to it and Bluetooth was the least expensive solution for connecting the speaker.
- 4. We noticed distortion and lack of clarity in the microphone sound, and it took a while to solve this problem by replacing it.

4.5 Summary

In this chapter, software implementation tools and a general description of the working steps of the smart cradle system were explained, and how it works integrated to achieve the previously mentioned functional requirements.

Then we discussed the mobile application, what are its interfaces and contents, and an explanation of each of them. We concluded the chapter with the challenges and problems that we faced during the implementation period and how we worked on them to complete them. and implement the smart cradle project successfully.

CHAPTER FIVE TESTING AND RESULT

5.1 Preface

This chapter includes hardware and software testing, analysis, and discussion about the result and recommendations based on the result.

5.2 Validation and Testing

In this section, we describe our hardware and software systems.

5.2.1 Hardware Testing

We tested the connection of Raspberry Pi 4 and sensors, DC (wiper) motor, web camera, and heater.



Figure 5. 1 Final Connection of The System



Figure 5. 2 Connection on The Cradle



Figure 5. 3 The Smart Cradle

5.2.2 Software Testing

During the software testing process, we conducted various tests to ensure that all of the features of the software were working properly. One of the tests involved connecting to Firebase and sending and receiving data from it.

We also tested the application, another important test was the ability to display notifications coming from Firebase on the phone. In addition, we also tested the validity of the machine learning results in distinguishing between dangerous and healthy positions for the baby, Testing the speed the DC motor swung the bed was an important test.

All of these tests were successfully passed, which demonstrated the reliability and robustness of the software. Table 5.1, Table 5.2, and Table 5.3 show some of the tests that we have carried out.

Table 5. 1 Unit Test

Case	Expected Output	Problem while working	Obtained Output	Pass/ Fail
Connect to the internet	Connect to the internet	The problem when we connect Raspberry to the internet Solving this by writing a set of commands	Connect to the internet successfully	Pass
Connect to firebase	Connect to firebase	Problem with the configuration of the necessary settings, solving this by getting the SDK file	Connect to Firebase successfully	Pass
Send and Get data to/ from the database	Send and Get data to/from the DB	Getting API Key by a set of steps to solve the configuration problem	Send and Get data successfully	Pass
Get data from sensors	Get data from sensors	Problem in wiring sensors, solving by fixing it well	Get data successfully	Pass
Get live stream from the camera	Get live stream	The problem when taking a capture and making a decision this will	Get live stream successfully	Pass

		take time so can't make a live stream, Solve by using another camera		
Get voice from microphone	Get voice	The problem is that the microphone was not receiving a clear sound. Solved by replacing the microphone	Get voice successfully	Pass

Table 5. 2 System Test

Case	Expected Output	Problem while working	Obtained Output	Pass/Fail
DHT11 sensor measures the temperature around the baby	Read the temperature around the baby	No problem	Read The temperature around the baby successfully	Pass
DC motor swing the cradle	Cradle is swinging	No problem	Cradle is swinging successfully	Pass
The heater turns on automatically when the temperature around the baby is under 25°	Heater runs automatically	No problem	when the temperature around the baby is under 25°, the Heater runs successfully	Pass
The fan turns on automatically when the	Fan runs Automatically	No problem	when the temperature around the baby is above	Pass

temperature around the baby is above 27c			25°, the Fan runs successfully	
The pulse sensor measures the baby's heart rate	Read the baby's heart rate	No problem	Read the baby's heart rate successfully	Pass
MCU30205 sensor measures the baby's temperature	Read the baby's temperature	Problem in wiring sensors, solving by fixing it well	Read the baby's temperature successfully	Pass

Table 5. 3 Application Test

Test	Result
Alert parents if the baby is not in the cradle	Pass
Alert parents when the baby sleeps on his stomach	Pass
Alert parents when the baby cries	Pass
Parents can create an account	Pass
Parents can log in to their account	Pass
Parents can send a voice record to the baby	Pass
Parents can control in wiper motor	Pass
Parents can control in heater and fan	Pass
Alert parents if the baby's temperature is higher than 37	Pass
Alert parents if the baby's heart rate is higher than 160 or lower than 80	Pass

Figure 5.4 shows the application test result if the baby is sleeping on his stomach, which constitutes a dangerous position.

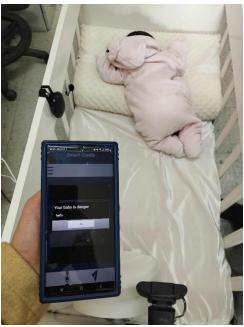


Figure 5. 4 Notification for Sleeping On Stomach

Figure 5.5 shows the application test result if the baby is covered, which is a danger position according to SIDS.

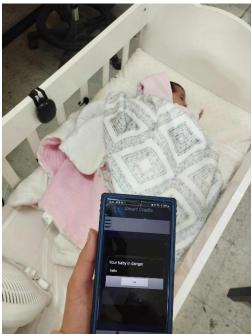


Figure 5. 5 Notification for Covered Baby

Figure 5.6 shows the application test result if the baby does not exist in the cradle.

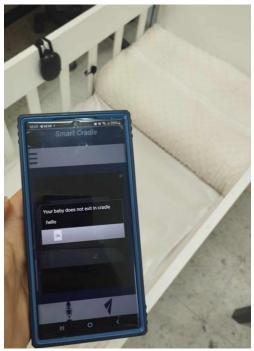


Figure 5. 6 Notification for Not Exist Baby

The project team noticed that the newborn baby to 6 months, has less movement and his positions are somewhat clear, as it was easier for the smart cradle system to determine whether they are dangerous or safe with more accuracy. However, after the age of 6 months, he is sitting or sleeping in undefined positions as usual. The smart cradle system was unable to determine the exact results of these positions, as mentioned in the Figure 5.7 below.



Figure 5. 7 Baby Position after 6 Months

5.3 Result and Discussion

Initially, there were several goals in this project to help parents with many of the problems they face in baby care, specifically Sudden Infant Death Syndrome(SIDS). This was achieved through the system, which consists of many sensors, electronic parts, and a microcontroller, which would help parents stay informed of the baby's status and some of his vital signs, through a mobile application.

These components were programmed to fulfill the requirements of the smart cradle system that were mentioned previously. Each component was examined separately, and then this system was built and the necessary tests were conducted to ensure that it works as required and whether it achieves the goals of its construction or not.

It can be said that the project, which targets babies from one day to six months of age, has achieved the desired goals required by the smart cradle system.

As this system takes data from the sensors correctly, the Raspberry Pi 4 microcontroller controls the environment of the smart cradle, based on the reaction based on the capture that is taken if the baby is in the cradle and a safe position, and if the baby isn't in the cradle, or sleeping on his stomach, or if he is in a danger position, the system sends an alert to the application, and in both cases, the parents can monitor the baby through the live stream.

5.4 Summary

In this chapter, the system was tested in three stages. In the first stage, the sensors, electronic parts, and devices were tested separately and after ensuring their correctness, moving to the second stage, which is testing the operation of the system after connecting the electronic parts to the microcontrollers, according to the flow charts in the third chapter. Then, in the final stage, the application was tested to ensure the integration of the entire system.

CHAPTER SIX

CONCLUSION AND FUTURE WORK

6.1 Preface

The chapter introduces a summary of the project, the future directions, and future work.

6.1 Conclusion

Smart Cradle system focuses on designing and developing a customized and expandable smart cradle system aimed at helping parents take care of their babies. smart system uses the latest technology to control and monitor a set of parameters necessary to follow the baby's condition by creating an audio and visual model using machine learning.

At the end of the project, we were able to monitor the baby's condition, which might expose him to sudden death syndrome, and the environmental temperature.

We were able to control the temperature around the baby in cold temperatures, vibrate the bed if the baby cried, and create a connection between the baby and the parents where the parents could watch and talk to the baby. Finally, we were able to build a prototype that implements functions that meet the functional requirements of the project. We found that it worked successfully.

6.2 Future Work

In the future, we look forward to adding important features to the system, the most important can be:

- Adding cases other than sudden infant death syndrome.
- Add memory to the system.
- Further classification of the causes of baby crying.
- Dispense with Wi-Fi service by providing it with a chip.
- Provide the system to be based on IOT.

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